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J. M. H. Candrews C.1 CR-133997

E-2785

MISSION SL-3 (AS 207/CM 117/IMU 31)
G&N ERROR ANALYSIS
(SKYLAB 3)

by S.B. HELFANT

July 1973







The Charles Stark Draper Laboratory, Inc.

Cambridge, Massachusetts 02139

(NASA-CR-133997) MISSION SL-3 (AS 207/CM 117/IMU 31) G AND N ERROR ANALYSIS (SKYLAB 3) (Draper (Charles Stark) Lab., Inc.) 31 p HC \$3.75 CSCL 17G

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Approved:

J.P. GILMORE

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o.g. Hoag

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The author wishes to acknowledge the contributions made to this report by Julius Feldman. Mr. Feldman helped in the review of this and previous reports and many of his suggestions have been included.

This volume is the combined effort of the following additional people; Linda Willy who prepared the component performance tabulation and performed the plotting for the inertial components. William Beaton provided the failure rates for the success probability. Their contribution to the preparation of this volume is greatly appreciated.

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The publication of this report does not constitute approval by the National Aeronautics and Space Administration of the findings or the conclusions contained herein. It is published only for the exchange and stimulation of ideas.

E-2785

MISSION SL-3 (AS 207/CM 117/IMU 31) G&N ERROR ANALYSIS (SKYLAB 3)

ABSTRACT

This document presents data on G&N system performance and operation for the CM. For data on the effects of Block II and of measured CM IMU test data deviation uncertainties on earth orbit insertion indication uncertainties and on deorbit burn and reentry uncertainties, the reader is referred to E-2760, the G&N error analysis report for Skylab-2.

by: S.B. Helfant July 1973

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GYRO DRIFT TEST POSITIONS FOR SUNDANCE, LUMINARY, COLOSSUS, AND ON

STABLE MEMBER POSITION	STABLE MEMBER ORIENTATION	HORIZONTAL DRIFT	VERTICAL DRIFT
1	X DOWN Y SOUTH Z WEST	NBDY-ADOAY	
2	X DOWN Y WEST Z NORTH	+NBDZ-ADOAZ	-NBDZ+ADIAX
3	X SOUTH Y WEST Z DOWN	NBDX-ADOAX	
4	X EAST Y SOUTH Z DOWN	+NBDY+ADSRAY	+NBDZ+ADIAZ
5*	X WEST Y UP Z NORTH	+NBDZ-ADSRAZ	
6*	X SOUTH Y DOWN Z EAST	+NBDX+ADSRAX	-NBDY+ADIAY
7	X NORTH Y UP-WEST Z UP-EAST	-NBDX+(ADSRAX/√2)	
8	X EAST Y UP-NORTH Z UP-SOUTH	$(-NBDZ-NBDY)/\sqrt{2}$ + $(ADIAZ-ADIAY)/2$ + $(ADSRAY+ADSRAZ)/2$	
9	X UP-EAST Y UP-WEST Z SOUTH	-NBDZ+(ADSRAZ/√2)	
10	X UP-NORTH Y UP-SOUTH Z EAST	(NBDY-NBDX)/√2 +(ADIAY-ADIAX)/2 +ADSRAX/2	
11	X NORTH Y WEST Z UP	-NBDX-ADOAX	
12	X UP Y SOUTH Z EAST	+NBDY+ADOAY	
13	X UP Y EAST Z NORTH	+NBDZ+ADOAZ	
			7

 $^{^{*}}$ Positions 5 and 6 are lab test only.

SKYLAB 3 G&N MISSION RELIABILITY ANALYSIS

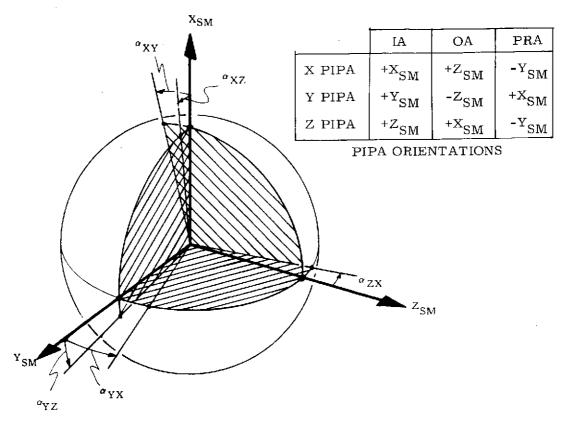
Failure rates used were obtained, for the most part, from observed Apollo field and flight experience of the PGNS. Each reported failure was analyzed with respect to its likelihood of occurrence in flight and the impact on the Mission should such failure occur. The result was to count only those reported failures which could occur in flight and which would degrade the Mission, should they occur. For the D&C Assembly the failure data was insufficient to form a meaningful statistic; therefore, the originally estimated failure rate was used.

SUBSYSTEM	MODE (time/cycles)	FAILURE RATE (λ×10 ⁶)	MISSION DURATION (hrs or cycles)	e-\lambdat
AGC	Operate Calendar Envirn. On/Off	19.2 2.8 30.9 238.1	37 1346 . 45 2	.99929 .99624 .99998 .99952
DSKY*	Operate Calendar Envirn. On/Off	1.4 .9 122.9 1190.5	37 1346 . 45 2	.99999 .99999 .99999
IMU CDU**	Operate Calendar Envirn, On/Off	20.2 2.4 62.5 1666.6	37 1346 . 45	.99925 .99677 .99997 .99667
IM U	Operate Calendar Envirn. On/Off	94.1 2.6 18.5 142.9	37 1346 . 45 2	.99652 .99651 .99999 .99971
IMU Electronics (PSA)	Operate Calendar Envirn. On/Off	8.4 1.2 18.5 714.3	37 1346 .45	.99969 .99839 .99999 .99857
Optics Assembly	Operate Calendar Envirn. On/Off	119.3 1.8 18.5 238.1	37 1346 . 45 2	.99560 .99758 .99999 .99952
Optics Electronics	Operate Calendar Envirn. On/Off	17.2 7.1 18.5 142.9	37 1346 .45	.99936 .99049 .99999 .99971

G&N MISSION RELIABILITY CM = .95999

^{*}Considers parallel redundancy $(1-(1-e^{-\lambda t})^2)$

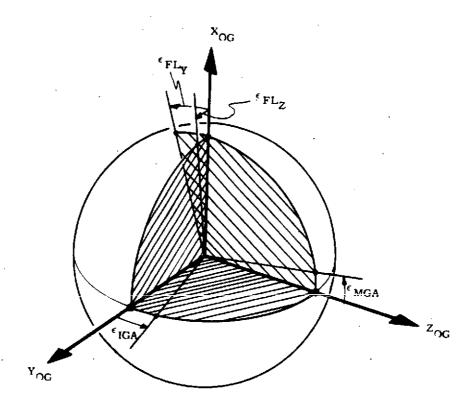
^{**}Includes CM Optics CDU



PIPA Misalignments from Ideal Stable Member Axes

	(Angle in Sec)
Term	CM-IMU 31
$^{lpha}_{ m XY}$	+24-
$\alpha_{ m XZ}$	0
$\alpha_{\mathrm{Y}Z}$	-18
$\alpha_{ m YX}$	-16
$^{lpha}_{ m ZX}$	-19

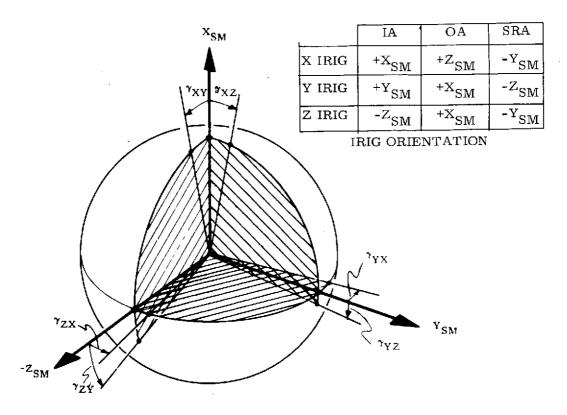
DEFINITION OF POSITIVE SENSE
PIPA INPUT-AXIS MISALIGNMENTS
with respect to
IDEAL STABLE MEMBER AXES



Gimbal Axis Orthogonality Errors and Outer Gimbal Misalignment from Casemounting Axes

	(Angle in Sec)
Term	CM-IMU 31
$\epsilon_{ m IGA}$	-18
$\epsilon_{ exttt{MGA}}$	-2
$\epsilon_{ t FLY}$	+6
$\epsilon_{ ext{FLZ}}$	-8

DEFINITION OF POSITIVE SENSE
GIMBAL AXIS ORTHOGONALITY
and
OUTER GIMBAL ALIGNMENT
with respect to
CASE MOUNTING ALIGNMENT



IRIG Misalignments from Ideal Stable Member Axes

(Angle in Sec)
CM-IMU 31
-34
+12
+22
+5
-91
+23

Block II G&N
DEFINITION OF POSITIVE SENSE
IRIG INPUT-AXIS MISALIGNMENTS
with respect to
IDEAL STABLE MEMBER AXES

IMU S/N 31 AS207/CM 117/G&N 221

 IRIGs
 PIPAs

 X = 8A211 X = 2AP82R

 Y = 8A212 Y = 2AP264R

 Z = 8A210 Z = 2AP91R

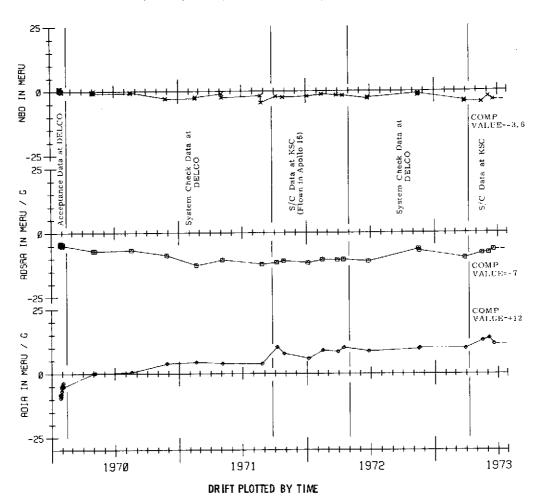
			TST		GEN								WHEI					
DI	ATE	roc	TYP		SYS			ADSRA	A	DIA	DELSF+					Ι÷	ID	A DO A
10	7 P C Q	A45					-											
		A45						0.00		4 01			C126				40.7	
				67 0	, 53.0	. የተ	;; (-	. V.B.) (1.6)			C131				10.7	
23	D P69	343	755	07.0	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	111))	2 6	03. \ /_	1 & 65			105				0 0	
29	D E69	A43	CSS			11.2) (- !) (-	3.7) (- } /-	1 11			102				8.0 9.4	
30	D B69	A43	CSS		•		., (3	, ,	1. 17			190				7.4	
				ECT									1,70					
		A44									4.8	109	196		85-001	85.003		•
				IF /	R4 & R	5 REVE	RSED .	RES	OLDEI	RED 8	REVERIE	'IED	.,,		03.001	03.003		
		A44		,				,					193					
16.	J A 70	144	CSS								110	184	198		85.001	85.004		
19:	J A 70	DEMO	T/F	= 11	93													
19	J & 70	A44	CSS								93	177	193		85.000	85.003		-
23	J A 70	VIB	IA	ALIGN	= -1.	1												
		A44				0.4		4.4	-	8.4								
		A44				1. 1		4.4	-	9.4	327	433			85.008	85.010	10.8	
		A44				0.7		4.8	-	8.1			195				•	
		A44				0.4	-	4.1	-	7.9								
		A44				0.4	-	4.5	-	8.8	441	276			85.004	85.005	11.4	
		A44				0.1	-	4.5	-	7.8			195					
		A43				1.0		4.6	.	6.8	_							
		A43				0. 2		4.5	-	4.9	424	399			85.008	85.008	11.3	
		A43			^ m==	0.0		4.7		5.6			188		-			
		A43		AOID							THER REP	. ONLY						
		A43				- 0.1 - 0.1	-				270	4.33			25 222			-
31.	3 A 7 O	143	CC3			0.4		4.9 5.3		5.0	379	437	106		82.008	85.008	10.5	
2 10 21	9 7 7 N	843	CC 1			- 0.4				4.4 3.6		-	196					
21	PE70	A43	CC2			- 0.4		4.4	_	4.7	483	11.6.11			95 000	85.009	40 h	
		A43				0.0		4.9	_	5.2	403	707	190	514	63.009	63.009	10.4	
				/O TO	0814		•	** /		J. 2			170	ा प				
						U 29 X	POSIT	'ION.	REPI	ACES	7C-199.							
	1R70													520				
3 0	A P70	A03	SPO	X 29		- 0.3				0.1								
				X 29		- 0.8	-	7.1					C131	547				- 0.2
18	4 Y 7 0	A03	SPO	X 29							20 7	507			85.019			
				X 29		- 0.0	ı			0.1								
				X 29		- 0.8	-	7.1						616				- 0.2
				X 29						0.6					-			
		A03				- 0.5	-	6.8			_							- 0.1
		M03									340	541		685	85.020			
		NO P	ruid	TRAN	SIENTS	DETEC	TED DU	RING	GRAV	ITY	TRANSIEN	T TEST.	•					
	1070	. 0.2	ana :	w 30		~ ^								715				
		NO3				- 2.9		0.0		3.9			0435					
		A 0 3				- 3.0	_	8.8			241	247	C134		05 644			- 0.6
	E70	A03	3FU	A 29							216	317		000	85.013			
		THIT	C / W ')	IPPED	EDOM D	ምና /ሐ ሆ፤	י תייחי י	ren					804				
57 C	A/1	1 40	3/N .	27 ON.	TELED	IRUE D	CL/END	, ju e	(3 6 •	_								

3FE71 INU S/N 29 SHIPPED FROM KSC TO DELCO/MKE.

		TST	TI	٤U	GEN		•						WH E					
DA T B	LOC	ΤYΡ	A S	SSN	SYS		N BD	ADS	RA	ADIA	DELSF+	DELSF-	RDT	HOURS	I+	I-	10	A DOA
400 004																		
18P E71						-	2.8	4.0		4.4	204	504			05 000			۰.
19FE71						-	2. 3	- 12	/		294	584			85.020			- 0.5
21FE71	A 0.3	SPO	X	29									C138	0.0				
26FE71														969				
84 R 7 1	104	CDO		20			1 0			7.0				9 71				
49 Y 7 1						_	1.0	40		3.9								- 0.5
59 Y 7 1 69 Y 7 1						-	2.5	- 10	• 0		307	534			85.011			- 0.5
					ICTRES	ים הי	마마다	דפמה חש	W.C	GRAVITY	-				05.011			
175 Y 71	NO.	LLUI	<i>D</i> 1	. RAS	PATERI	ι 3 μ.	BIECI	ומטע עם	. N G	GRETILI	INANSIE	MI 1631	•	972				
	TME	C / N	20	e p	TODE	יסים ר	3 M D E	L/#KE T	·	פר				712				
								DEFCO\										
241 071							1.8	Durco	11114	3.8								
25A U 71						_	4.5	- 12	. 3	3.0			C133					- 1.1
26A 1771							78.7	, ,	• • •		350	561	C140		85.013			, , ,
31A U71	,	510	•	2,							330	50.	Ç I TÜ	1072	03.013			
	IMU	29	SHI	PPE	D FRO	M D	E LCOZ	MKE TO	KSC	! .								
60 C 7 1						_		- 11		10.3	- 19	- 45						- 0.1
260 C71						-		- 11		7.8	_	- 150						- 0.4
47 172						-	2.0	- 11	-	5.8								- 0.5
14P E72	K 9A	G&N	X	29	216	-	1. 3	- 10	. 6	9.0								- 0.5
29F E72														1249				
285 R 72	K9A	GE N	X	29	216	_	1.7	- 10	. 7	8.5								- 0.4
14A P72	K 9A	GE N	X	29		-	1.8	- 10	. 6	10.1								0.0
										ADSRA -1	1.0 AD	IA 8.0						
16AP72																		
										0 HRS. 0	6 MIN. (GET						
27h P72					6 CM-			VERED A	POL									٠
241 272						-	3.0		_	8.7								•
24JE72						-	2.5	- 11	. 2		417	617			85.003			
9N 072																		
					TO			- POS. R	EPL	ACES 9A		277			05 006			
159072						-	7.7.			9.7	7	273	~133		85.006			
15N 072							1.7	- 6	. 4	10.0			C133					
17N 072							1. 3	- 7		10.0								
17072					CTPUT		1.1 *********			GRAVITY	прамстрі	***						
20N O 72	NO I	LLOI	<i>U</i> 1	n n n	DIEN!	יט כ.	SINCL	דשמת תם	n G	TILARNE	INNBSIE	MI 1831		1898				
289 R73	CDE	CDA	v	71		_	3.8			9.9	265	480	C131	1030	85.005			- 0.5
28N R 73							4.3	- 9	_ Q	7 . 7	205	400	C131		60.000			- 013
					D PRC			ro KSC.					C ()					
12A P73																		
30A P73	T 10 4 7	. nau.		4 (3	- te 1 1			•						1967			•	
169 Y 73	KOB	GE N	X	31	221	_	4.5	- 8	.0	12.9	172	26		,,,,,				0.4
4JE73						_	-	- ž	-	13.8	204	255						0.4
18J E73		_				-	3.6		.7	11.6	'							0.4

œ

G&N 221, CM 117, IMU 31, APOLLO IRIG 8A211, X AXIS

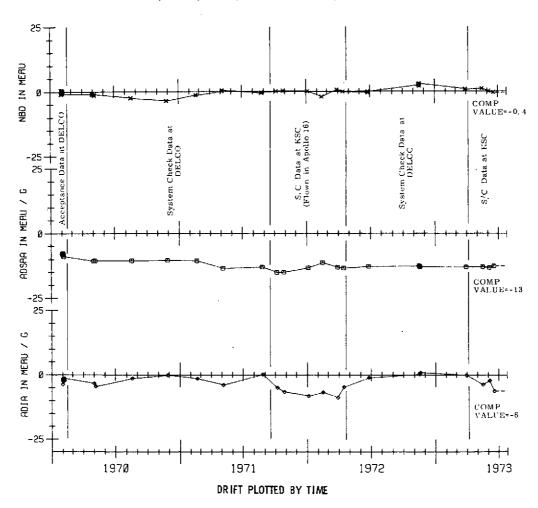


		TST		GEN										WHE					
DATE	LOC	TYP		SYS			_	ADSRA		ADIA	DI	ELSF+	DELSF-	PDT	HOURS	I+	I-	ID	A DO A
63 A 7 O	A 4 4	CSS					_							C134					
					(6.8)	(-	1.0)	(-	1.0)								5.0	
7J A 70	SG 8	14.5,	70.2	, 59.	3	TG 56	.9,	70.3,	80.	, A			REF H5	421					
13JA70 16JA70	<u> 144</u>	CSS			(7.7)	(-	3.2	(-	0.7)				186				6.9	
16JA70	A45	CSS			(7.7)	(-	3.2	(-	0.7)				184				4.7	
16JA70			EC.											187					
28J A 70	NAS	CCC DET	EUT								_	294	200	176		84.997	P# 006		
281170	COMP	. U.S.S	TF								_	2.74	230	170		04.777	04.790		
28J A 70 28J A 70 28J A 70 28J A 70 29J A 70	A45	CSS									_	218	122			84.997	84.996		
29J A 70	DEMO	T/	P = 1	223												,	4.0550		
29J A70	A45	CSS									-	239	321	178		84.997	84.996		
29J A 70	VIB	IA	ALIG																
31JA70					-	0.9	-	8.0	-	1.6									
31J A70					-	1.1	-	8.0	-	2.3	-	249	642			84.998	84.996	6.3	
31J A70						0.9 1.1 0.6 0.0 0.2 0.4 0.1	-	8.0	-	3.7				185					
2F E 7 0						0.0	-	8.3	-	2.4		20	620			94 999	94 006	<i>5</i> 2	
2F E 70					•	0.2	_	8.3 7.7	-	1.5	-	28		188		04.995	84.996	5.2	
4P E70					_	0.4	_	8.5	_	2.0				100					
4F E 70					_	0.1	_	8.4	_		-	180	471			84.997	84.999	6.1	
4F E70						0.8	-	9.0	_	1.4		,		187					
1 0F E 70			/0 TO	0814															
189 R70	UNIT	ASS	IGNED	TO I	MO	29 Y	POS I	rion.	REP	LACES	71	-198.						•	
314 R70															704				
30A P70						1. 1			-	3.3									
301 P70					-	0.7	-	10.7					£0.4	C133					- 1.1
18 170			_			1.5				4.5	•••	50	584			85.018			•
5% ¥70 5% ¥70					_	1.0	_	10.6							795				- 1.2
17A U70					_	2.4		10.0	_	1.4					733				- 144
17a U70					-	2.4 2.6		10.6		. •									- 1.2
18A U70								-				127	784		869	85.019			
24% 070	NO P	LUID	TRAN	SIENT	S D	e tect	ED D	FRING	GRA	VITY !	r R A	NSIEN	T TEST.						
251 U70															898				
26NO70						3.6			-	0.1				C130					
27NO70					-	3 . 6	-	10.4				227				05 012			- 1.3
30NO70	AU3	SPO	1 29									221	794		988	85.012			
9D E 70 5J A 71	THU	5 / N	20 CH	TODEN	T D	O B DR	T /H R 1	ያ ጥብ ሄ	90						700				
3F E71																			
19F E71					_	1.3				1.5									
19FE71					-	1.5	-	10.6											- 1.2
21F E71	A 03	SPO	¥ 29											C136					
22F E 71	X 03	SPO	Y 29									273	951		4==-	85.020			
26F E71				,											1053				
81 R71 51 Y71	801	c pA	v 20			0.1			_	3.9					1055				•
54 Y 7 1						0.5	_	13.5	-	3.7									- 0.8
64 Y71						~ • ~		• 5				343	955						V • U

		TST	INU	GEN						WH E	EL				
DA TE	LOC	TYP	ASSN	SYS	N BD	ADSRA	ADIA	DELSF+	DELSF-			I+	I-	ID	A DOA
104 971	NO 3	9 T 11 T	D 10 D 3 3	ic Tena	c namacen	D DUDING						85.010			
174 Y 71	NO I	. 70.7	DIMA	ADTENI:	S DETECTE	D DURING	GRAVITY	TRANSIE	AT TEST		4466				
	Tan	S/N	29 51	ITPPED	FROM DEL	/MKE TO R	rec				115 5				
9a u71	IMU	29	SHTPP	D PRO	N KSC TO	DELCO/MKE	2.								
25A U71					- 0.6	DEECO, IIKI	0.2	4							
25a U 71					- 0.3	- 13.0	912			C 134					- 0.9
26N U71	A 0 1	SPO	¥ 29					474		C139		85.018			. – U•9
31A U71											1256				
225 E71	IMU	29	SHIPPE	ED FROM	B DELCO/S	KE TO KSC	:.								
63C71					0.1	- 15.1	- 5.0	88	755						0.5
73 C7 1)N 8	0.3		- 10.8								
260C71					0.3	- 15.0	- 6.6	36	640						- 0.3
260 C 71							- 1.6								
4JA72					0.1	- 13.3									- 0.1
4J A72 14F E72					- 2.0	44 3	- 7.5								
14F E72					- 2.0	- 11.3									0.5
29F E72	VDT	ii P	031110	/N O			- 3.5				4.50				
284 R72	KOB	GE N	w 29	216	0.7	- 13.1	- 8.8				1432				
284 R 72					0.7	- 13.1	- 7.0								- 0.3
148 P72				,,, ,	- 0.1	- 13.4									
148 P 72				N 8	. .	13.4	- 6.4								0.0
					ATIONS: N	BD -0.4	ADSRA -	14_0 ADT	A -7.0			÷			
16AP72	IMU-	-29 (GE N-21	6 CM-1	113 LAUNC	HED APOL	LO 16.		,						
17a p72	NBD	COM	PENSAT	ION UE	PDATE = -	0.13 AT 3	O HRS. ()6 MIN. G	ET						
27A P72	IMU-	-29 (G&N-21	6 CM-1	113 RECOV.	ERED APOL	LO 16.								
24J E72							- 1.1								
24JE72					- 0.0	12.8		441	1152			85.004			
					INU-29.										
				TO IN	10-31, Y-	POS. REPL	ACES 9								
15N 072					2.5	40.5	0.3	150				85.006			
158072 178072						- 12.6				C137					
178072 178072					2.0 3.0	- 13.0	0.9								
				STRNOS		D DURING	CD147774	MD ANGTEN	M MBcm						
201072		DOI:	<i>,</i> 1 11 11 11	2.4.011.17	Duibers.	D DUNING	SERVILL	TRANSLEN	T TEST		2071				
295 R73	SB5	SPO	Y 31		0.9		- 0.1	350	1070	C125		85.005			
298 R 73					0.8			3.70	1070	C133		03.003			- 1.5
				D FROM	DELCO TO					C 13.3					
					AT KSC.										
30a p 7 3											2150				
16M Y73	KOB	G& N	Y 31	221	1. 1	- 12.9	- 3.8	148	993		• , • •				- 0.6
164 473							- 5.6								
4JE73					0.1	- 13.2	- 2.2	124	1124						- 0.4
4JE73							-6.2								
18J E73					- 0.4	- 12.6	- 6.3								- 0.3
18JE73	ANTA	t PC	51T10	n 8			-4.9								

11

G&N 221, CM 117, 1MU 31, APOLLO IRIG 8A212, Y AXIS

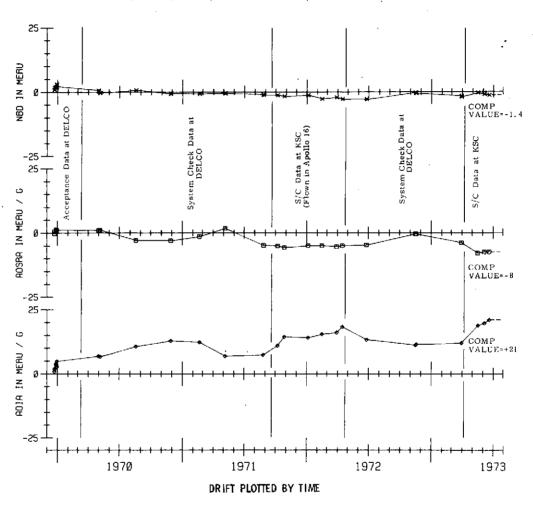


		TST	INU	G&N									WHE	EL				
DATE	LOC				N BD	A D	SRA	ADIA	DE	LSF+	DEI	SF-	RDT	HOUPS	I+	r-	ID	ADOA
3D E 6 9	A45	CSS											C122					
40 E 6 9	A45	CSS		(36.0)	(-	1.8)	(2.0)					C119				16.5	
40 E 6 9	SG	36.4,	67.3	, 50.3	TG 50.	5, 67	4.	(2.0) 87.3 (2.6)		Į	REF	R54	18					
5D E69	A45	CSS		(35.8)	(-	1.5)	(2.6)					C122				16.2	
50 E 6 9	3 9	SERVO) RERU	N WITH	CW VALU	IE AT	0.0	493 - 51	TLI.	oos								
5 D E 69	A45	CSS		{	34.6)	(-	0.4)	(3.6) (2.0) (3.2)					C122				17.0	
100 E69	A 4 1	CSS		(36.1)	(-	1.9)	(2.0)					177				16.6	
16D B69	A41	CSS		(34.4)	(-	1.4)	(3, 2)					179				14.7	
17D E69	A41	CSS											180					
210 869	CON	P SEI	ECT															
21DE69	A43	CSS								44		146	173		85.010	85 .010		
22DE69	CON	B AEB	RIF.															
22D E69	A43	CSS								13		105			85.010	85.010		
220 E6 9	DEM	T	YF =	1182.6														
22D E 69	A43	CSS							-	114		88	177		85.009	85.009		
220 E69		_			1.15													
22D E69					0.9													
220 E69	A43	CA 2			1.0		0.3	0.9		37		263			85.011	85.011	15.3	
22D E69 27D E69	A43	CA3			1.8 1.8		0.6	1.0					171				,	
270 E69 270 E69	A43	CBI			1.8		0.8	4.0								45 44		
							1.3	3.4		93		3/9	475		85.012	85.012	14.9	
27D E 69					1.8 2.9		0.8	3.8					175					
29D E69					2.9		1.2	2.8 2.6		244		245			05 00"	05 666	40.0	
29D E69									-	211		215	40.0			85.006	14.8	
290 E69				01276			1. 1	4.9					180	494		•		
				C1276		\^ C T M Y	-011		20	400								
	UNI	r ass	LGNED	TO In	U 29 Z F	05111	.ON.	REPLACES	70	- 180.	•			504				
31M R70		cno	er 20		Λ.6			6.9					C124	501				
30A P / U	AUS	SPO	7 20		0.6 0.2		1 0	0.9		4 E A	_	104	C 124	52 7				0.0
- 5% ¥70	203	SPO	2 29		- 0.3		1.0	6.7		100	_	104			03.010			0.0
53 Y 7 0			7 20		- 0.3		1 1	0.1						E 0.7				- 0.1
174 070			7 20		0.4		1. 1	10.7						J#1				- 0.1
17A U70			7 20		- 0.4 0.7 0.7	_	2.9	10.7										- 0.5
18A U70					U. /	_	2.0			20.0	_	100		666	85.020			- U.S
				CTRNTC	D R ጥዌርጥ E	ם חת מי	TNC	GRAVITY	T D A					000	03.020			
25AU70	HO .	LOIL	LUAN	STHRIS	DHIBCII	ib bul	LING	GKKILLI	1111	H O X II.	ar 1	. 1 1	D	696				
26NO70	B 0.3	SPA	7 29										C127					
					- 0.7			12.9					C 12 /					
27x070	103	SPO	7. 29		- 0.7 - 0.6	_	3.0	,										0.6
30n 070					0.0		J. U			140	_	150			85.010			V • 0
90 E70	** ***	510	-							1 T V				785	VJ - V 1 V			
	INU	S/N	29 sн	IPPED	FROM DEL	/HKE	TO K	SC.						, , , ,				
					FROM KSC													
19F E 71					- 0.7			12.3										
19F E 71					- 0.7	-	1.4	,										0.0
21FE71					-								C126					
22FE71										350	_	83			85.019			
26F E 71			-											850				
85 R71														852				
1 - 4 -5 1 1																		

NASA BA-210

		TST	IM	IJ	GEN										WH'31	EL				
DATE	LOC	TYP	AS	SN	SYS		N BD	A D	SRA	ADIA	DE	LSF+	ÐΕ	LSF-	RD'T	HOURS	I+	I -	ΙD	ADOA
50.774																				
54 Y 71						-	0.4		4 0	6.9										- 0.1
54 7 7 1						-	0.6		1.8			34.0		4 11 10			85.012			- 0.1
64 771									T 11 G	~ D . W T M W		340		140			03.012			
	NO	FUIT	υT	KAN	PIENT	5 D	EISCIN	אנוע ע	110	GRAVITY	TRA	MOTE	Νí	IESI.	•	952				
175 771	T #17	~ (1)	20	G !!	T D D D D	. ED	A BEF	/# W TO	m 0 1/2							902				
16JE71																				
9AU71 25AU71					D FKO		0.9	DELCO	Amve	7.4										
-							1.2	_	4.9	/ = 4					C125					- 0.3
26AU71 27AU71						_	1. 2	_	4.3			407		7	C127		85.013			- 0.3
318071	AVI	310	4	29								401		,	C 12 /	1053	03.013			
225 871	TMI	20	CUT	DDE	חמב חי	ar bi	2 T C O / M	KP ጥብ	R SC							1055				
60C71						- I	1.3		5.1	11.0	_	17	_	535						0.2
262C71						_	1.7		5.7	14.4		83		534						0.2
4JA72						_	1. 3	_		14.1		53		334						0.3
14F E 72			_			_			5.0	15.5										0.2
29F E72	>	351	-	 /			-• .			,3,3						1230				
281 R72	KQA	GEN	7.	29	216	_	2.1	-	5.4	16.1						. = 0				0.0
14A P72							2.8		5.0	18.3										0.1
			_		MPENS					ADSRA -	5.0	A D	IA	14.0						
16AP72										LO 16.										
17AP72	NBD	COM	PEN	SAT	ION U	PDA'	r	2.45	AT 3	O HRS. 0	6 8	IN.	GET							
271 P72	IMU	-29	G&N	-21	6 CM-	113	RECOV	ERED	APOL	LO 16.							-			
24J E72	A01	SPO	Z	29		-	2.8			13.3										
24JE72	A 01	SPO	Z	29		-	2.9	-	4.7			461	-	83			85.003			
911072	UNI	r RE	MOV.	ED	FROM	IMU-	- 29.													
9N 072	UNI	r As	SIG	NED	TO I	MU-3		POS.	REPL	ACES 94	-01									
15#072	595	SPO	Z	31		-	0.2			11.2		60	-	351			85.003			
15NO72						-	0.3	-	0.4						C124					
178072	SB5	SPO	Z .	31		-	0.5			11.5										
17N 072						-	9.6	-												
18N 072	NO 1	PLUI	D T	RAN	SIENT	S D	ETECTE	D DUR	ING	GRAVITY	TRA	NSIE	NT	TEST						
20m o 72																1869				
29MR73						-	1.7			12.0		339	-	165	C126		85.007			0.0
294 R 7 3	-					-	2.0	-							C128					
3h P73								O KSC	•											
12A P73	INS'	PALL:	ED .	ÍΝ	CM-11	7 A:	r KSC.													
301 P73			_		205									11.10.00		1947				. .
169 Y 73						-	0.5	-		18.8	-	19		448						0.4
4JE73						-	1.0		7.5	19.7		158	-	427						0.2
18J E73	кув	G& N	Z	5 T	221	-	1_4	-	7.5	21.0										0.2

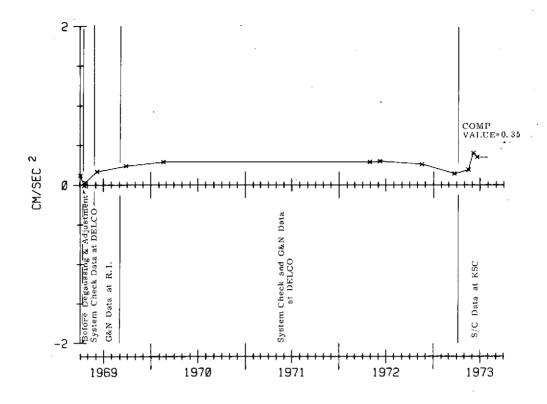
G&N 221, CM 117, IMU 31, APOLLO IRIG 8A210, Z AXIS



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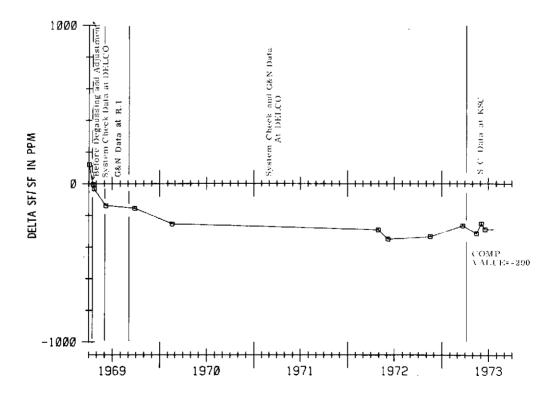
ማም ልብ	ז.סכ ז	rst ryp	IMU ASSN	GEN SYS	DEL	TA F	TG BIAS	N U B I	LL AS	ROT-A	L-WOB	TRANS.	TORQ MON CURRENT
							REBUILT	TO	P/N	20011	730-2		
17DE68	542 7	ACC.			-	65	0.00					0.02	105.6074
•	REPAIR	חשכ	HHTT	DET T	חססקט	TO	AC-MET						
2AP69		PST			1	19	0.12			- 4	8		
21 P69	UNIT	ASS	TGNE	ከ ጥር ፣	TMU S	/N	31X						
164 P69	A05 S	5 P O	X 31		(2)	(-0.11)	(-0	. 14)				105.5872
174P69	A05 5	5P0	X 31		_	6	(-0.11) -0.01	-0	.02				105.5838
214 P69	A05 S	SPO	X 31		-	33	0.03	-0	.01				105.5838
22AP69	A05 5	SAL	X 31				0.03	(-0	.03)	17	29		
•	INU SA	/N 3	1 SH	IBBED	TO N	B							
6J E 6 9	NOZ 6	it N	X 31	218	- (40	U . 17						
	IMU S	5/N	31 SI	HIPPE	D TO	AC-	MKE						
263 E69	A03 S	5P0	X 31		- 1	5 7	0.24	0	. 21				105.5760
2 65 E6 9	RAN I	EO 3	596-	NULL	COIN	CID	ENCE CHE	CK					
263 E69	A03 5	SAL	X 31		_		0.29	(0	. 23)	11	26		405 5650
178 E 70	A01 S	SPO	X 31		- 2	56	0.29	. 0	. 29	_			105.5650
18FE70	A01 S	SAL	x 31		_			(0	- 24)	3	33		405 5560
28AP72	A03 S	5 P O	X 31		- 2	93	0.29	0	. 28	•	2.5	0.03	105.5660
25 772	A03 S	SAL	X 31				0.29	(0	. 25)	2	26		
6JE72	AOT C	38 N	X 31	213	- 3	51	0.30	_	0.0			0 03	405 5606
169072	SB5 S	SPO	X 31		- 3	34	0.26	. 0	. 26	_	2.2	0.03	105.5696
164072	SB5 8	SAL	X 31		_		0.41	(0	. 28)	.3	32	0 63	105 5670
22¶ R73	SB5 S	5P0	X 31		- 2	65	0.14	0	. 20	^	2.0	0.03	105.5672
274 R73	SB5 5	SAL	X 37				OT HOTOM	(U	. 34) m	U	24		
							OLUTION		T				
							TO KSC.						
12A P 73													
164 173													
4J E73													
18JE73	K9B 0	óΟN	1 t x	221	- 2	ゔヺ	0.30						

G&N 221, CM 117, IMU 31, APOLLO PIPA 2AP82R, X AXIS



1-G BIAS DRIFT PLOTTED BY TIME

G&N 221, CM 117, IMU 31, APOLLO PIPA 2AP82R, X AXIS



SCALE FACTOR DRIFT PLOTTED BY TIME

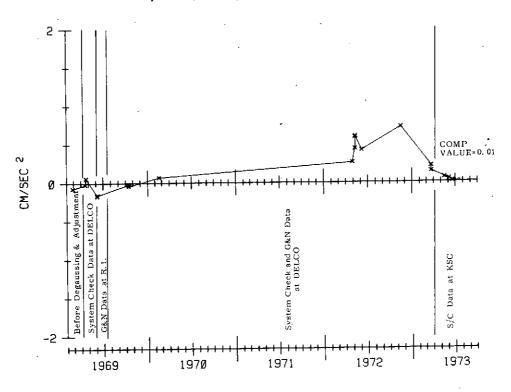
TST IMU GEN DELTA

18JE73 K9B G&N Y 31 221 - 460 0.01

NULL

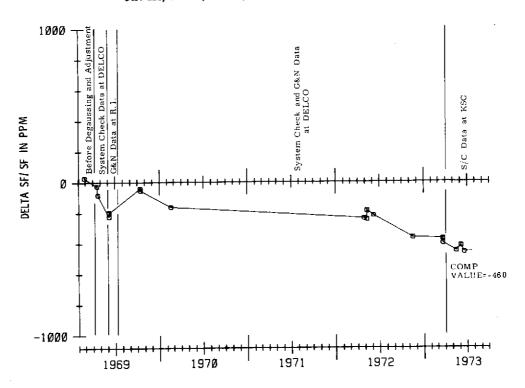
İG

ROT-AL-WOB TORO MON



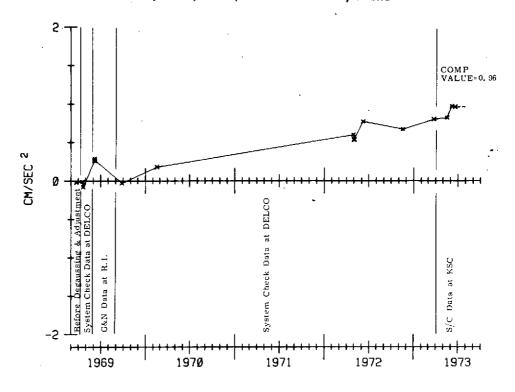
1-G BIAS DRIFT PLOTTED BY TIME

G&N 221, CM 117, IMU 31, APOLLO PIPA 2AP264R, Y AXIS



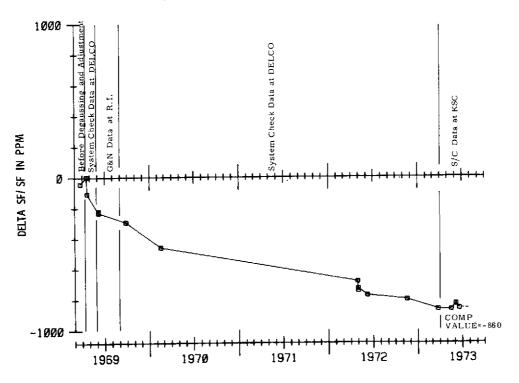
SCALE FACTOR DRIFT PLOTTED BY TIME

DATE	TST LOC TYP			DELTA SF	IG BIAS	NULL BIAS	ROT-AL-WOB ANGLE	TRANS.	TORQ MON CURRENT
	UNIT IN	TERNA	LLY RE	PAIRED.	REBUILT	TO P/N	2001730-2		
12DE68				1 72			8 - 7	0.05	104.3540
	REPAIRED	UNIT	DELIV	ERED TO	AC-MKE				
23% R69	A44 FST			- 42	-0.02		8 - 7		
21 P69	UNIT AS	SIGNE	TO I	MU S/N	312				
161P69	A05 SPO	Z 31		(410)	(-1.19)	(-1.16)			104.3980
174 P 69	A05 SPO	Z 31		3	-0.01	0.01			104.3820
211 P69	A05 SPO	Z 31		- 108	-0.08	0.01			104.3803
22NP69	A05 SAL	Z 31				(0.00)	- 16		
	TMIT C/N	41 CH:	י מפפסו	TO NR					
6J E 6 9	NO2 GEN	Z 31	218	- 232	0.26				
6J E 69	NO2 GEN	z 31	2 18	- 222	0.29				
6JE69	NO2 GEN NO2 GEN NO2 GEN	z 31	218	- 232	0.27				
	IMU S/N	31 51	HIPPED	TO AC-	MKB				
	A03 SPO			- 294	-0.03	0.02			104.3700
265 E69	RAN EO	3596-	NULL	COINCID	ENCE CHE	CK			
265 E69	A03 SAL	z 31				(0.02)	- 14 - 15 - 26		104.3710
17FE70	A01 SPO	Z 31		- 461	0.18	0.21			104.3710
18F E 70	A01 SAL	z 31				(0.23)	- 15		
284 P 72	A03 SPO	z 31		- 683	0.60	0.62			104.3694
11 Y 72	A03 SPO	z 31		- 744	0.53	0.56			104.3600
13 772	A03 SPO	z 31		- 731	0.54	0.58		0.03	104.3607
2M Y72	A03 SAL	Z 31				(0.58)	- 26	•	
44 ¥72	RAN EO	3700-	-PIPA	NULL RE	SOLUTION	TEST			•
	A03 SPO					0.64			
6J E72	AO1 GEN	z 31	213	- 774	0.77				
168072	SB5 SP0	z 31		- 802	0.67	0.71		0.05	104.3683
169072	SB5 SAL	Z 31				(0.71)	- 20		
23M R73	SB5 SP0	Z 31		- 864	0.80	0.82		0.03	104.3625
271 R73	SB5 SPO SB5 SAL SB5 SPO SB5 SAL	Z 31				(0.87)	- 19		
12AP73	INSTALLI	ED IN	CM-11	7 AT KS	C.		6		
CITIO	NOD GOM	4 .7 1		3 0 2	0.55				
	KOB GEN								
18J E73	K9B GEN	z 31	221	- 858	0.96				



1-G BIAS DRIFT PLOTTED BY TIME

G&N 221, CM 117, IMU 31, APOLLO PIPA 2AP91R, Z AXIS



SCALE FACTOR DRIFT PLOTTED BY TIME

STANDARD DEVIATION (1) OF THE IRIG AND PIPA PARAMETER UNCERTAINTIES USED FOR MISSION PERFORMANCE SUMMARY CM 116; IMU S/N 22

PARAMETER			
IMU Axis	<u>x</u>	<u>Y</u>	<u>z</u>
PIPAs			
Data Compilation Period 5/16/73-6/18/73 Accelerometer Bias (cm/sec ²) Scale Factor (SF/SF ppm)	0.09 26	0.02 18	0.07 15
IRIGs			
Data Compilation Period 5/16/73-6/18/73			
Bias Drift (MERU)	0.9	0.6	0.4
ADSRA (MERU/g)	0.6	0.2	0.2
ADIA((MERU/g)	0.9	1.7	0.9
ADOA (MERU/g)	0.0	0.1	0.1

Data is based upon performance in the IMU. Point-to-point stability operation is much better than the above data.

PARAMETER

PROPOSED GYRO AND ACCELEROMETER PERFORMANCE COMPENSATIONS

IMU Axis X Y \underline{z} PIPAs Accelerometer Bias (cm/sec²) +0.35 +0.01 +0.96 Scale Factor (SF/SF ppm) -290 -460 -860 **IRIGs** Bias Drift (MERU) -3.6 -0.4 -1.4 ADSRA (MERU/g) -7 -13 -8 ADIA (MERU/g) +12 -6 +21

Dictionary of Terms

ACC Acceptance TeBuData

ACD After Cooldown

ACE A.C. Electronics (presently Delco Electronics)

ADJ Adjusted

ADOA Acceleration Sensitive Drift Due to Acceleration along the OA

BCSW Binary Current Switch

BIA Bias Adjusted

BUSS High, Low, or Nominal Direct Current Test

CDN Post Cooldown

CQL Component Qualification
CRQ Component Requalification

CRR Retest After minor adjustment or Resistor Changes

CRT Retest Data

CSS Short Servo Test

CVR Component Verification

DGI Degaussed IRIG

DGS Degaussed

F/F Float Freedom
FST Final Stability

GAL Guidance & Navigation PIPA Alignment

G&N Guidance & Navigation System Measurement

GP Gaussed PIPAs HBS Hi Bus Voltage

I&A Inspection and AcceptanceISS Inertial Sub-System DataKSC Kennedy Space Center

LBS Lo Bus Voltage

MW Milliwatt

NAR North American Rockwell (presently Rockwell International, Inc.)

NBS Nominal Bus Voltage

OOS Out of Spec

RDT Wheel Rundown Time, Seconds

RI Rockwell International

PRECEDING PAGE FOR F

APPENDIX

ELECTRICAL POWER REQUIREMENTS

This section was extracted from the MIT/IL Report E-1142 (Rev. 59) "SYSTEM STATUS REPORT". It is included in this report for convenience.

Electrical power and energy reporting is based upon the inflight spacecraft sequence of events for the Design Reference Mission as developed by the Apollo Mission Planning Task Force (AMPTF). (Reference GAEC Report Volume III - LED-540-12, dated October 30, 1964).

The accompanying diagrams present the power drawn through the spacecraft circuit breakers. It is assumed that power is drawn from the spacecraft's primary +28VDC supply and a 400 cps-115 VAC single phase inverter.

Intermittent power peaks can exist, particularly during operation of displays and controls at random times. The energy content in these peaks is considered negligible.

All values (except those mentioned above) are actual expected levels of power at 28.0 VDC. They are based on measured values on G&N systems 207 and 208 for the Block II Command Module. No margin factor has been applied to protect against possible differences between G&N systems and spacecrafts. Thus, these values should not be taken as "not to exceed" extremes.

The following Interface Control Documents serve as the guidelines for reporting power figures.

CM Block II MH01-01327-216 "G&N Electrical Input Power" signed 15 July 1965.

BLOCK II GUIDANCE & NAVIGATION LOAD ON PRIMARY +28 VDC COMMAND MODULE

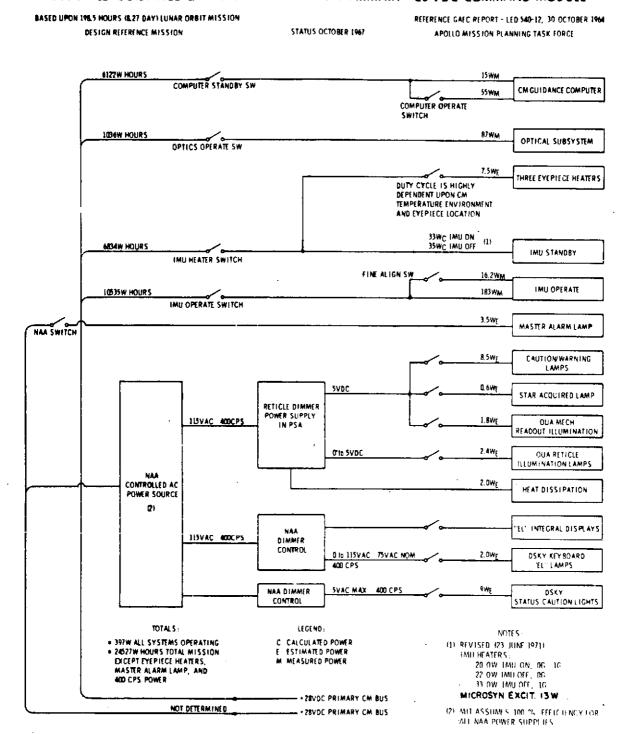


Figure A-1